

## CHAPTER 3

### Lists, Stacks, and Queues

#### §1 Abstract Data Type (ADT)

【 Definition 】 **Data Type** = { Objects }  $\cup$  { Operations }

【 Example 】 **int** = { 0,  $\pm 1$ ,  $\pm 2$ ,  $\cdot \cdot \cdot$ , INT\_MAX, INT\_MIN }

$\cup \{ +, -, \times, \div, \%, \cdot \cdot \cdot \}$   
【 Definition 】 An **Abstract Data Type** (ADT) is a data type that is organized in such a way that the **specification** on the objects and **specification** of the operations on the objects are **separated from** the **representation** of the objects and the **implementation** on the operations.

## §2 The List ADT

❖ ADT:

**Objects:** (  $\text{item}_0, \text{item}_1, \dots, \text{item}_{N-1}$  )


**Operations:**



**Finding the length**,  $N$ , of a list.

□ **Printing** all the items in a list.

□ **Making an empty** list.

□  **Finding** the  $k$ -th item from a list,  $0 \leq k < N$ .

□  **Inserting** a new item after the  $k$ -th item of a list,  $0 \leq k < N$ .

□  **Deleting** an item from a list.

□ **Finding next** of the current item from a list.

□ **Finding previous** of the current item from a list.



Why after?

# 1. Simple Array implementation of Lists

$\text{array}[i] = \text{item}_i$

Sequential mapping

Address	Content
.....	.....
$\text{array}+i$	$\text{item}_i$
$\text{array}+i+1$	$\text{item}_{i+1}$
.....	.....



**MaxSize** has to be estimated.



**Find\_Kth** takes  $O(1)$  time.



**Insertion** and **Deletion** not only take  $O(N)$  time, but also involve a lot of data movements which takes time.



## 2. Linked Lists

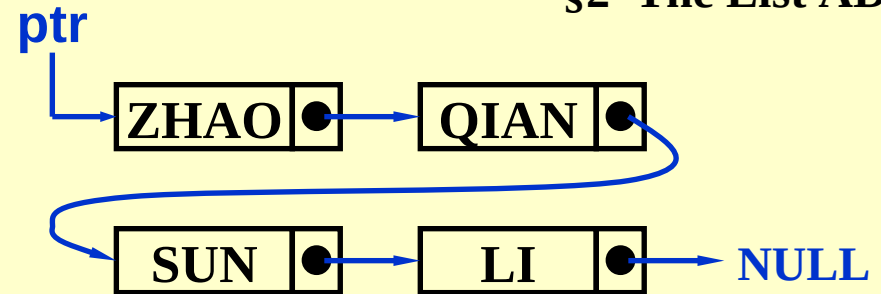
Address	Data	Pointer
0010	SUN	1011
0011	QIAN	0010
0110	ZHAO	0011
1011	LI	NULL

Head pointer ptr = 0110

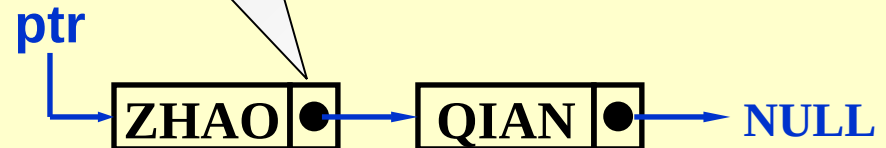
Initialization:

```
typedef struct list_node *list_ptr;
typedef struct list_node {
    char    data[4];
    list_ptr next;
};
list_ptr ptr;
```


Locations of the nodes may change on different runs.

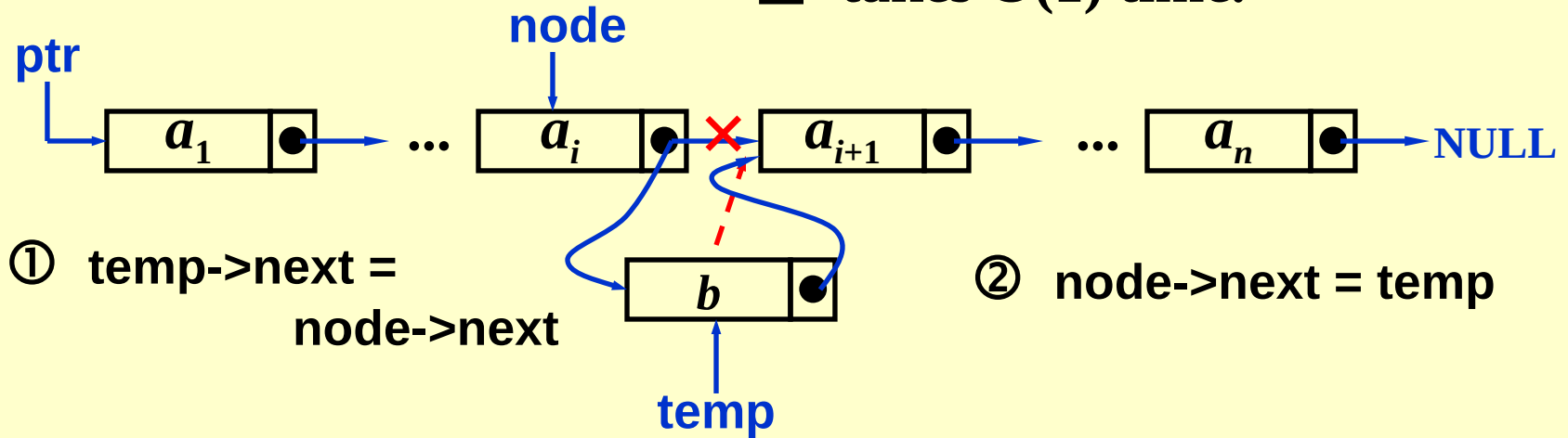


To link 'ZHAO' and 'QIAN':



# Insertion


 takes  $O(1)$  time.

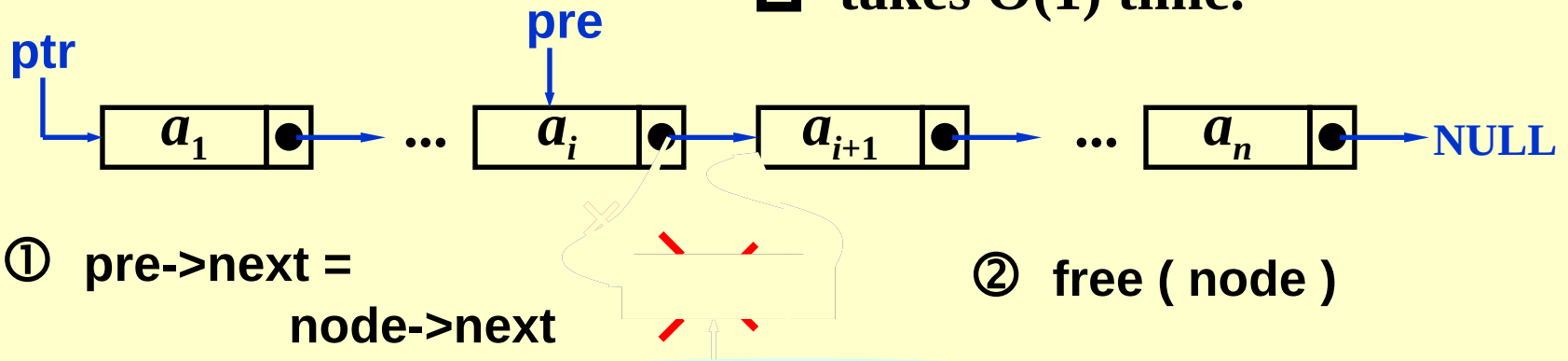


**Question: What will happen if the order of the two steps is reversed?**

**Question: How can we insert a new first item?**

# Deletion

 takes  $O(1)$  time.



**Question:** How can we delete the first node from a list?

**Answer:** We can add a dummy head node to a list.

Read programs in Figures 3.6-3.15 for detailed implementations of operations.

# Doubly Linked Circular Lists

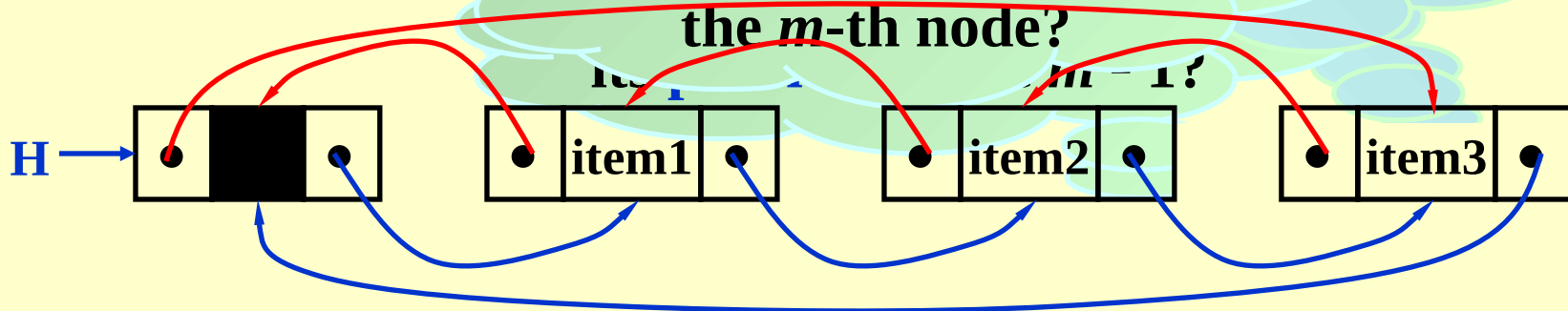
```
typedef struct node *node_ptr ;
typedef struct node {
    node_ptr llink;
    element item;
    node_ptr rlink;
};
```



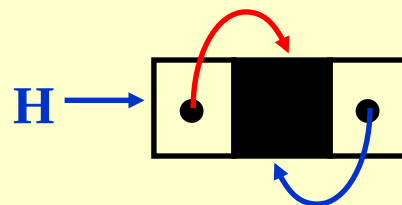
... Then I'll have to  
 ptr = ptr->llink->rlink  
 in the 1st node again.  
 y, why do I want to link->llink

Why do you ask me? :-)

A doubly linked circular list with head node  
 maybe you want to delete  
 the  $m$ -th node?



An empty list :



### ★ The Polynomial ADT

**Objects** :  $P(x) = a_1 x^{e_1} + \dots + a_n x^{e_n}$ ; a set of ordered pairs of  $\langle e_i, a_i \rangle$  where  $a_i$  is the **coefficient** and  $e_i$  is the **exponent**.  $e_i$  are nonnegative integers.

#### Operations:

- **Finding degree**,  $\max \{ e_i \}$ , of a polynomial.
- **Addition** of two polynomials.
- **Subtraction** between two polynomials.
- **Multiplication** of two polynomials.
- **Differentiation** of a polynomial.



## 【 Representation 1 】

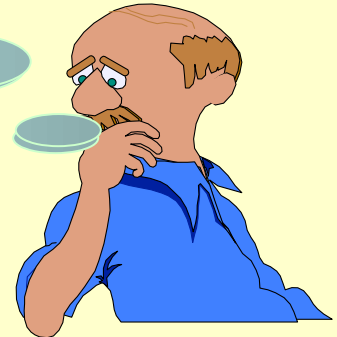
```
typedef struct {  
    int    CoeffArray [ MaxDegree + 1 ] ;  
    int    HighPower;  
} *Polynomial ;
```

Try to apply MultPolynomial (p.47)

On  $P_1(x) = 10x^{1000} + 5x^{14} + 1$  and

$P_2(x) = 3x^{1990} - 2x^{1492} + 11x + 5$

-- now do you see my point?

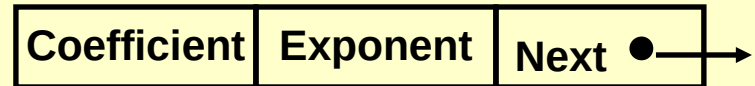


# 【 Representation 2 】

Given  $A(x) = a_{m-1}x^{e_{m-1}} + \dots + a_0x^{e_0}$

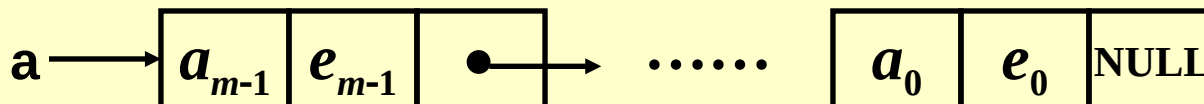
where  $e_{m-1} > e_{m-2} > \dots > e_0 \geq 0$  and  $a_i \neq 0$  for  $i = 0, 1, \dots, m-1$ .

We represent each term as a node



## Declaration:

```
typedef struct poly_node *poly_ptr;
struct poly_node {
    int    Coefficient ; /* assume coefficients are integers */
    int    Exponent;
    poly_ptr Next ;
};
typedef poly_ptr a ; /* nodes sorted by exponent */
```



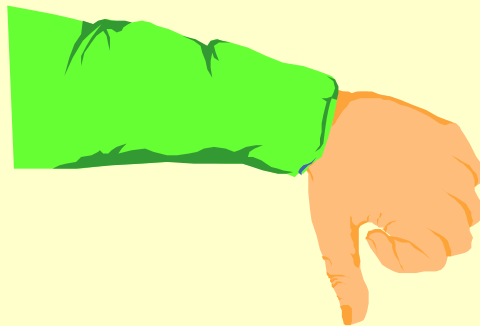
## ★ Multilists

【 Example 】 Suppose that we have **40,000** students and **2,500** courses. **Print** the students' name list for each course, and **print** the registered classes' list for each student.

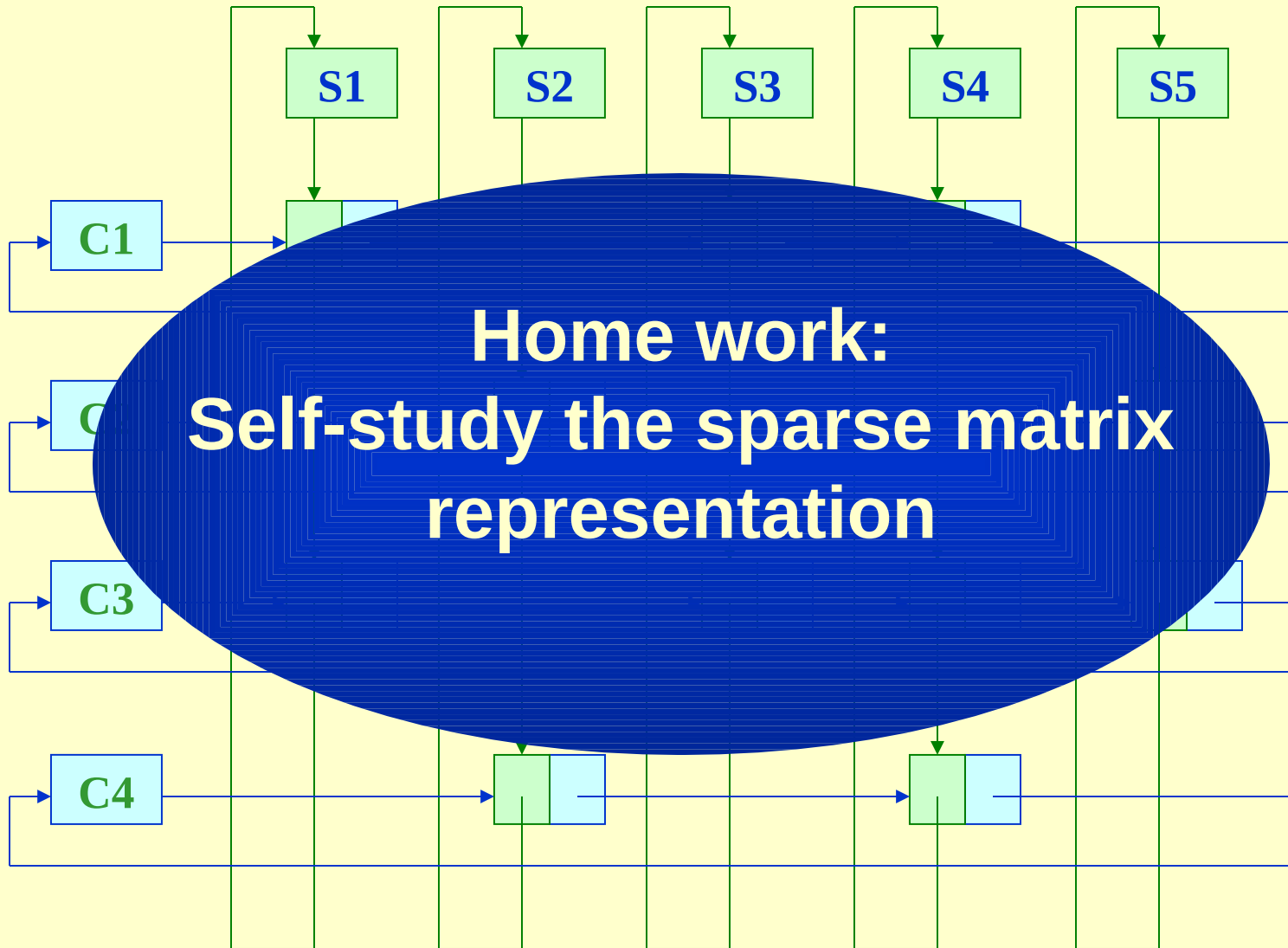
### 【 Representation 1 】

```
int Array[40000][2500];
```

$$\text{Array}[i][j] = \begin{cases} 1 & \text{if student } i \text{ is registered for course } j \\ 0 & \text{otherwise} \end{cases}$$



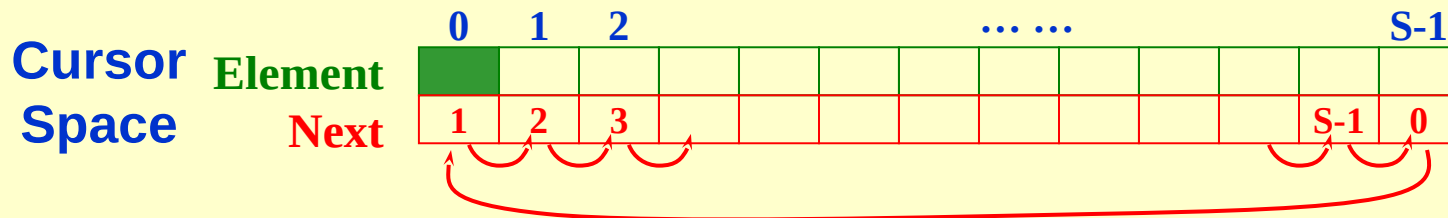
## 【 Representation 2 】



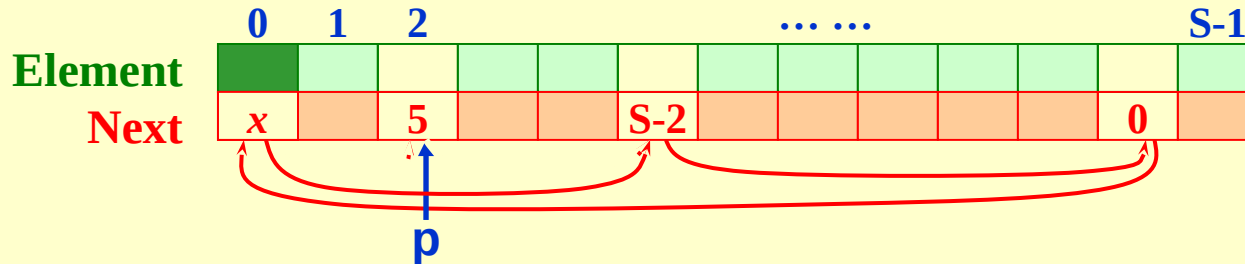
### 3. Cursor Implementation of Linked Lists (**no pointer**)

👉 Features that a linked list must have:

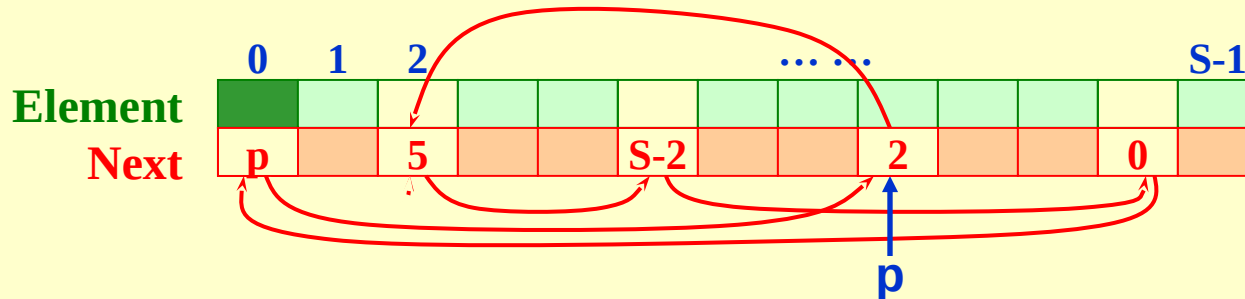
- The data are stored in a collection of structures. Each structure contains **data** and a pointer to the **next** structure.
- A new structure can be obtained from the system's global memory by a call to **malloc** and released by a call to **free**.



**Note:** The interface for the cursor implementation (given in Figure 3.27 on p. 52) is identical to the pointer implementation (given in Figure 3.6 on p. 40).



**malloc:** `p = CursorSpace[ 0 ].Next ;`  
`CursorSpace[ 0 ].Next = CursorSpace[ p ].Next ;`



**free(p):** `CursorSpace[ p ].Next = CursorSpace[ 0 ].Next ;`  
`CursorSpace[ 0 ].Next = p ;`

Read operation  
implementations given in  
Figures 3.31-3.35

**Note:** The cursor implementation  
is usually significantly **faster**  
because of the lack of memory  
management routines.